

SVT Timing Study Status

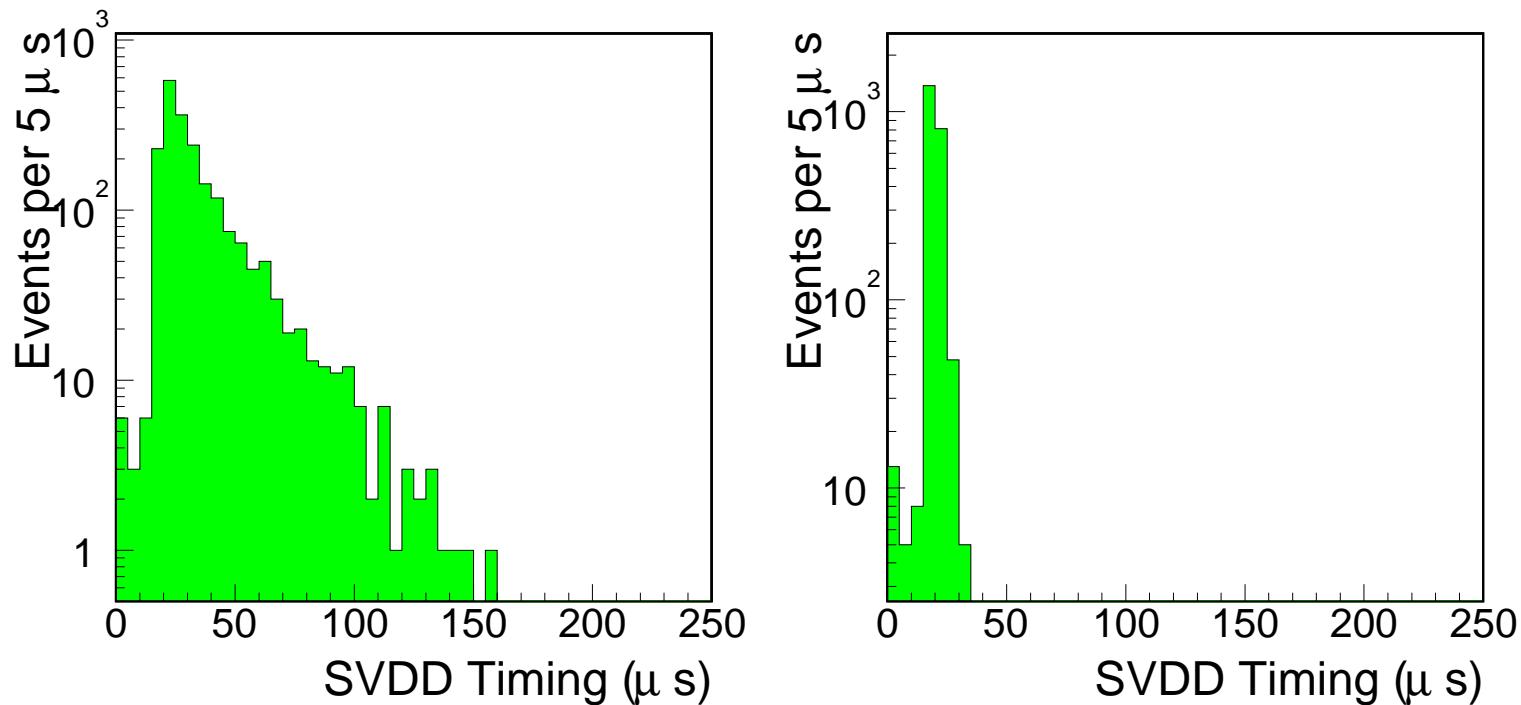
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SVT / TDWG Weekly Meeting, June 4, 2004

Overview:

- simple linear model
- performance for different luminosities
- parametrizing the environment
- performance of the parametrization
- this week's plan

Reminder: Clean timing measurement



- require L2 buffer 0
- require SVX back end state 0 (waiting for L1)
- significantly reduces number of “chopped” events

Timing Models:

Simple Linear Model:

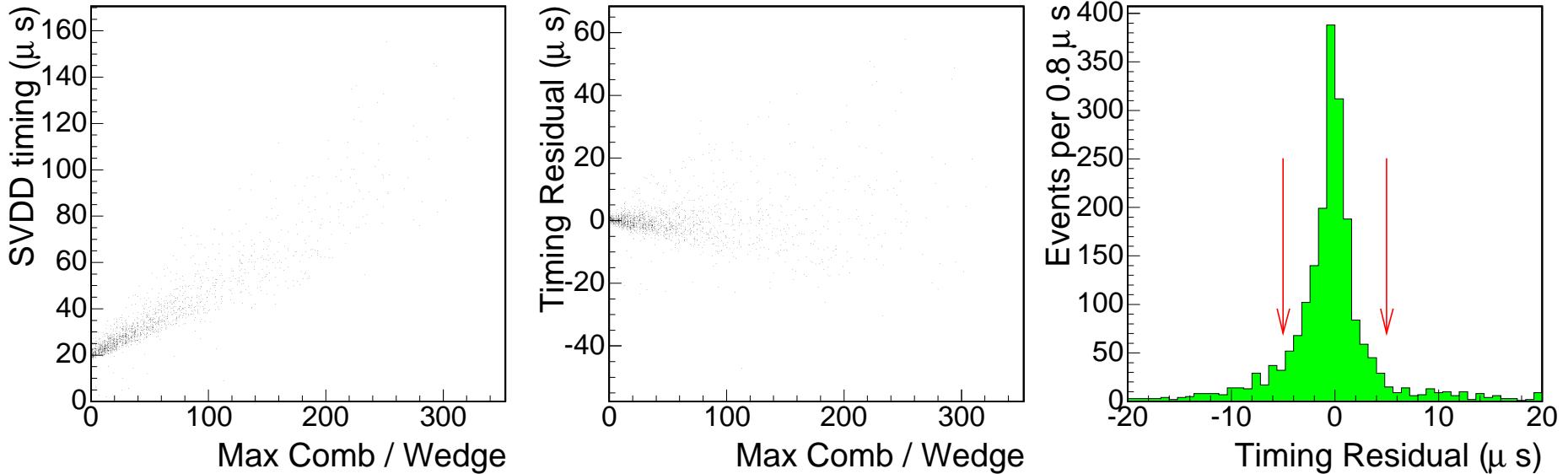
- assume hit loading time $\sim \max(N_{\text{hits}}^{\text{wedge}})$
- assume track fitting time $\sim \max(N_{\text{comb}}^{\text{wedge}})$
- these two effects drive SVT timing

More Realistic Model:

- assume single board can be linearized
- account for data flow interference and interaction
- outlined in CDF 5021
- not enough handles in data to tune model parameters

time is an issue: need working model quickly

Track Fitting Linearization:

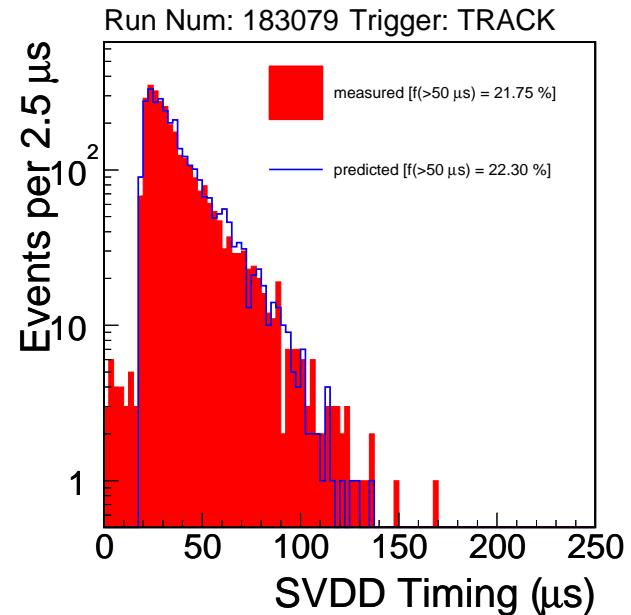
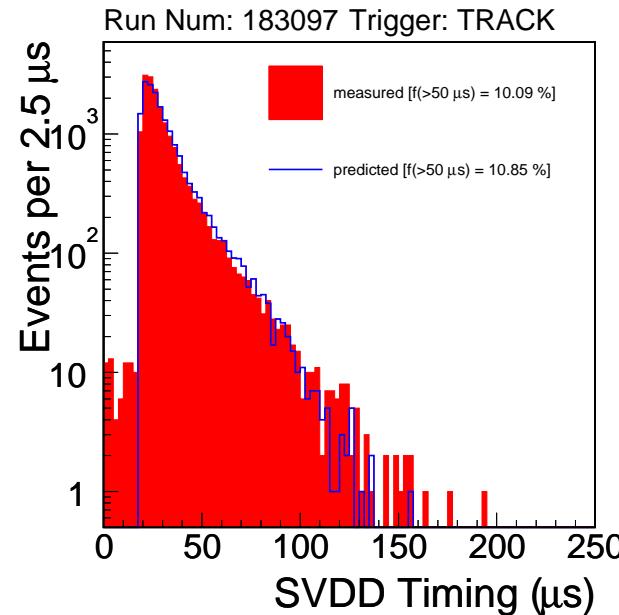
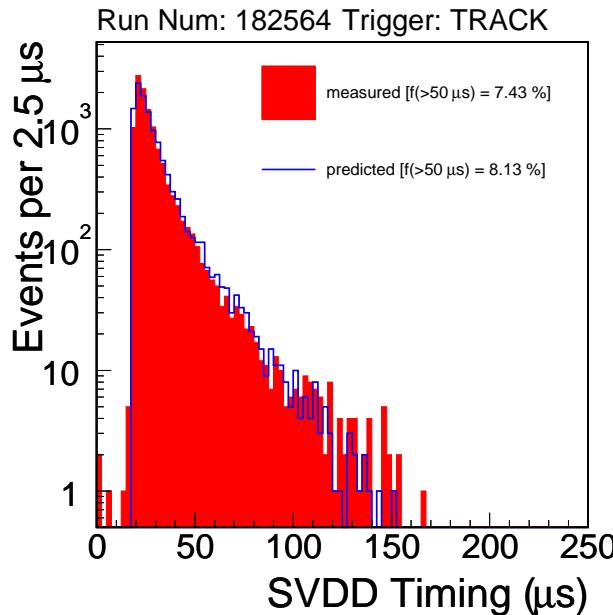
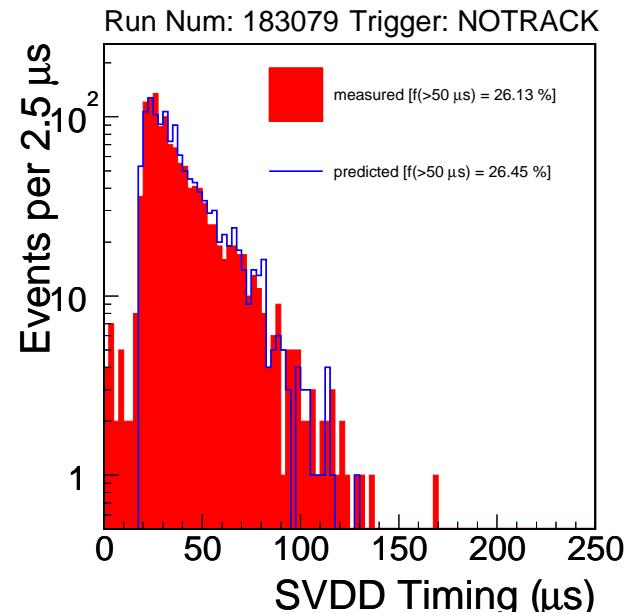
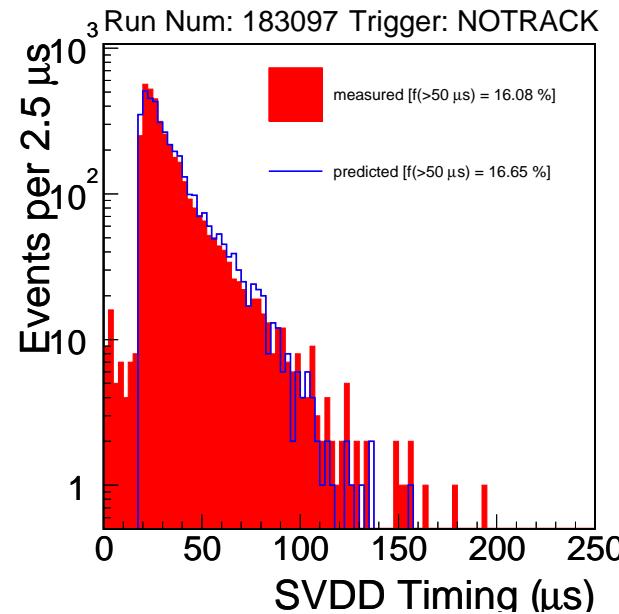
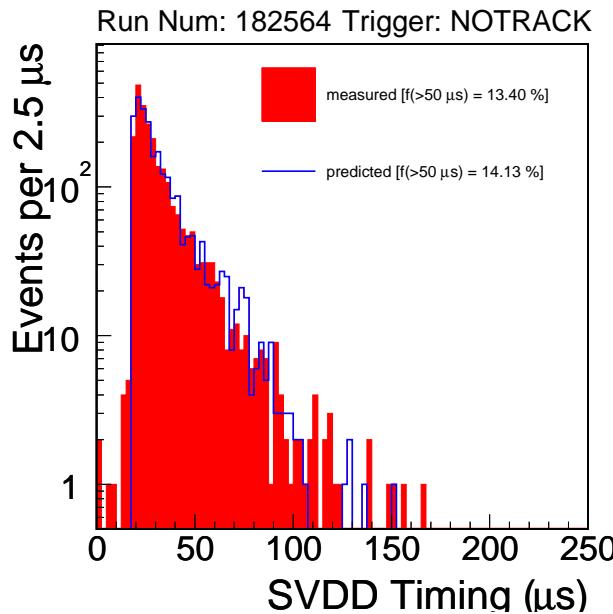


- low luminosity run
- in addition, scattered events
- residuals: 81% of events in $\pm 5 \mu s$ window
- central Gaussian width around $2 \mu s$

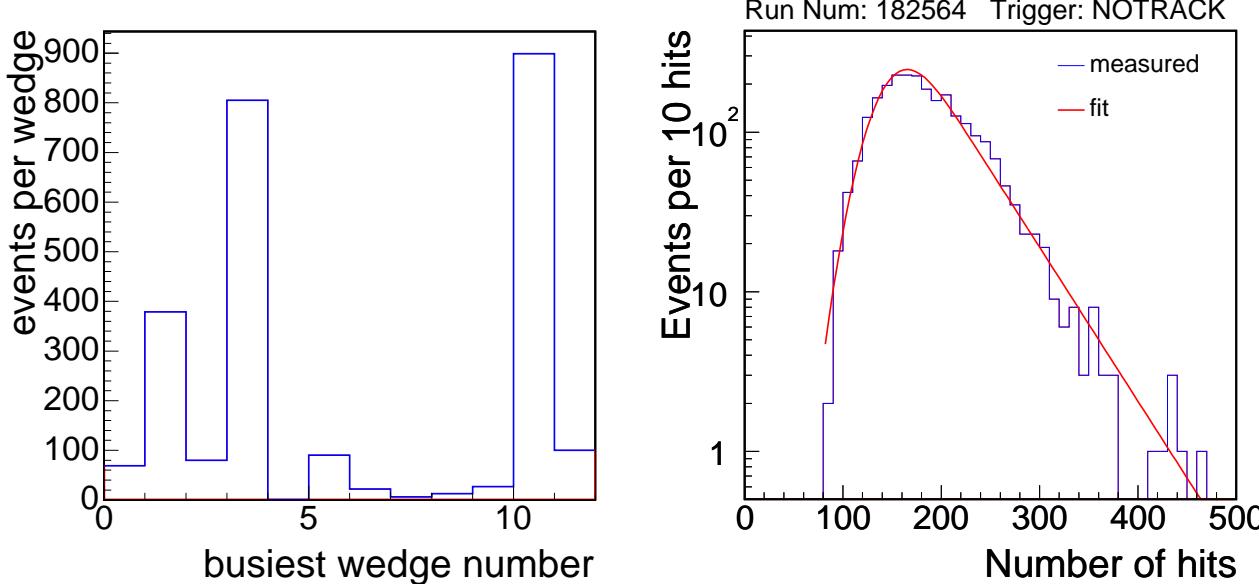
Tests of Simple Model Performance:

- compare measured SVDD timing to predicted
- base prediction on measured N_{hits} , N_{comb}
- three representative runs:
 - 182564 ($10 - 12 \cdot 10^{30}$)
 - 183097 ($17 - 25 \cdot 10^{30}$)
 - 183079 ($40 - 50 \cdot 10^{30}$)
- two representative (unbiased) triggers:
 - MONITOR_L2_INCLUSIVE_NOTRACK
 - MONITOR_L2_INCLUSIVE_TRACK
- quantify: fraction with processing time $> 50\mu s$
- as following slide will show, reasonably good agreement

Simple Timing Model Performance:

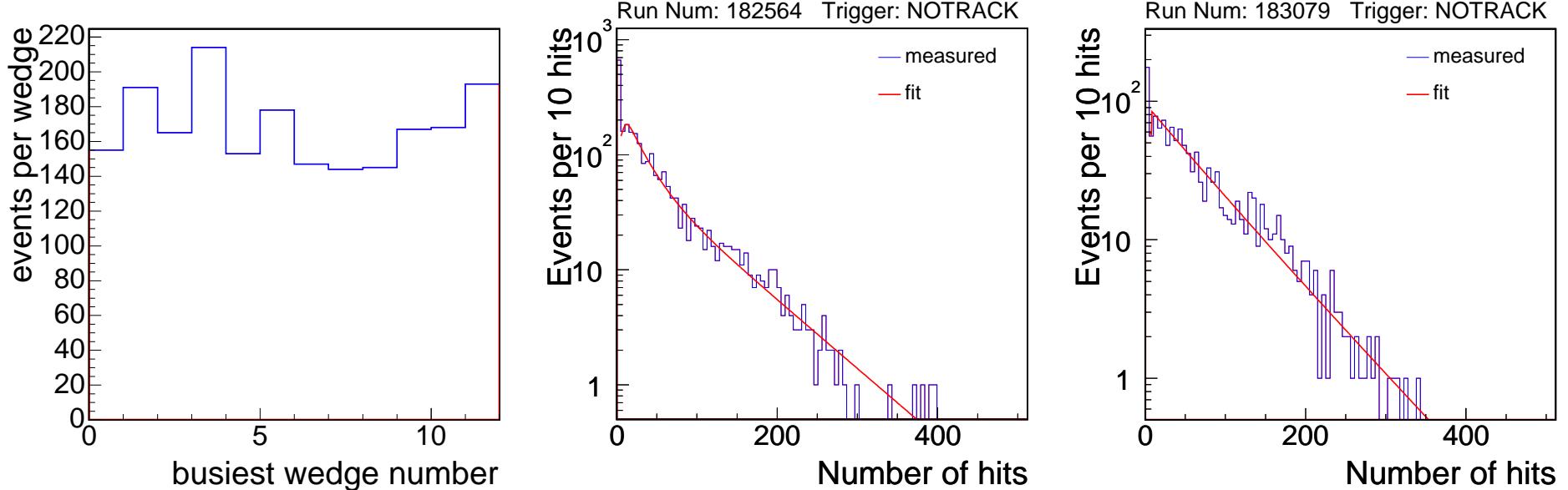


Parametrizing the hit distribution:



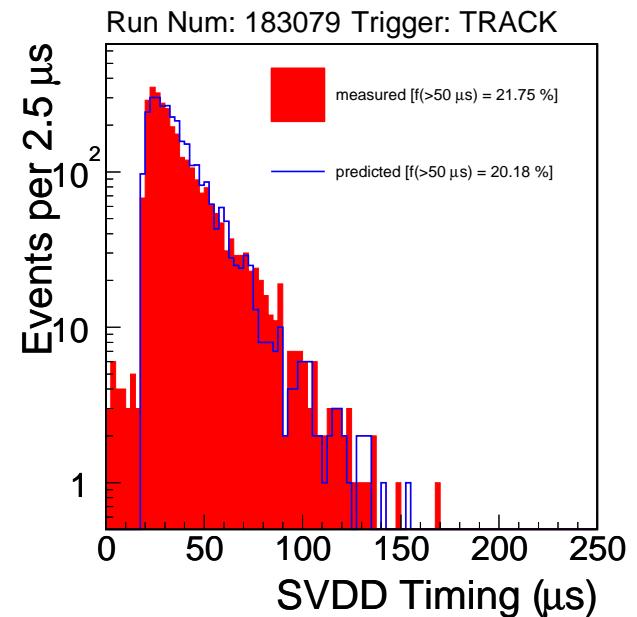
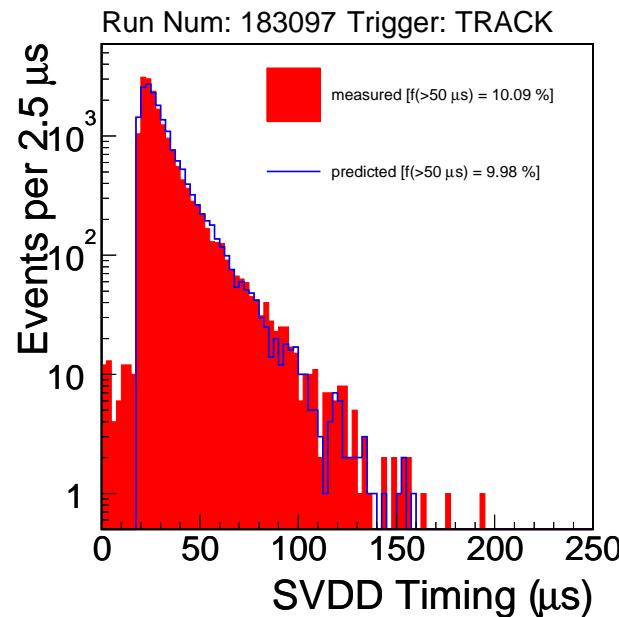
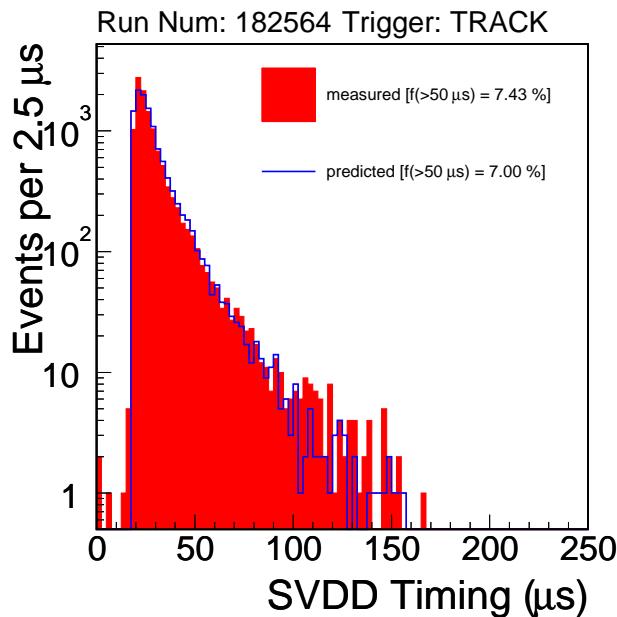
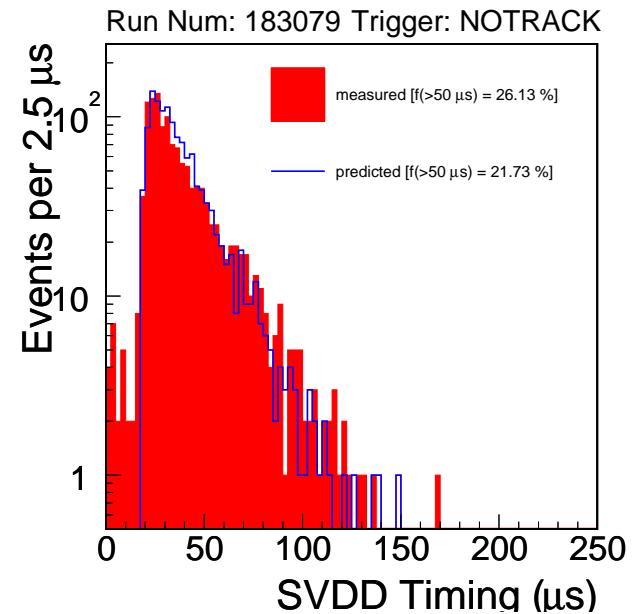
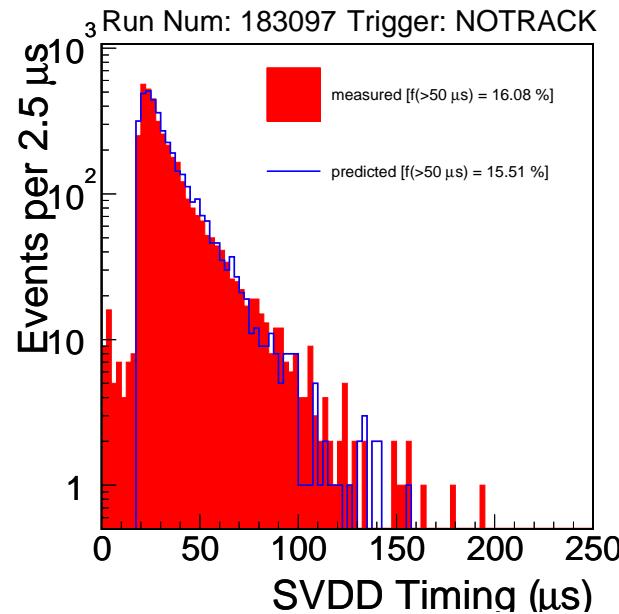
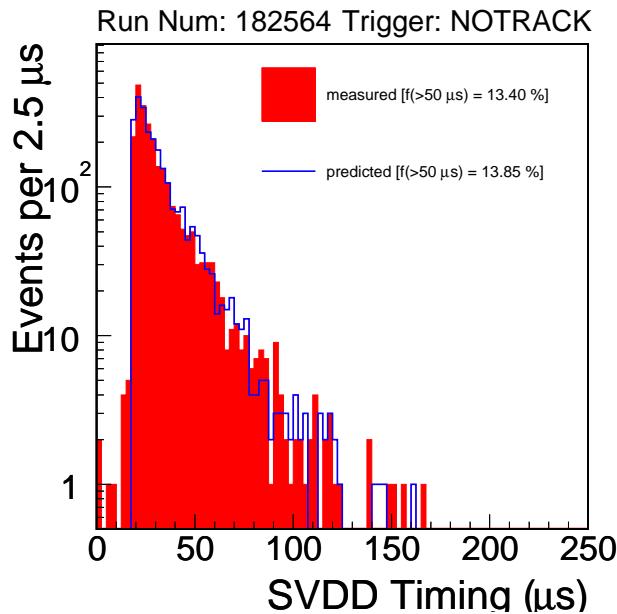
- take distribution of busiest wedge from data
- parametrize N_{hits} with gaus \otimes exponential
- seems to work well for all luminosities

Parametrizing Combinations:



- take distribution of busiest wedge from data
- parametrize N_{combs} with:
 - zero-bin fraction,
 - gaus \otimes exponential (low-comb shoulder)
 - + exponential (high-comb tail)
- describes lower lumi well, working on high lumi

Simple Timing + Parametric Env:



Test results:

- good description of low luminosity ($< 30 \cdot 10^{30}$) events
- less successful in describing higher luminosities
- problem: robust model for N_{combs} , working on it
- eventually: dependance of model parameters on \mathcal{L}
- this will then provide a method to predict the environment for $5e32$.
- use linear timing model to predict timing based on derived environment
- expect good timing prediction based on good environment prediction

SVT Timing Test Runs:

- setup so SVT timing should be understandable:
- eliminate wedge negotiation noise: run single wedges
- eliminate timing sculpting: run with single L1 buffer
- extra runs: two wedges, all wedges
- 14x50k events at low luminosity
- slowest, fastest wedge and 12 wedges at high luminosity
- triggers: two track, $Z \rightarrow b\bar{b}$ and no-track
- if possible, add pulsar → intermediate timing
- improve timing calibration, get more handles

Todo list:

- interface to ModSim with simple model, parametric env.
 - estimate how well these models work.
 - study scaling of environment variables with \mathcal{L}
 - establish timing model for pulsar SVT
(3x, 6x clock speed)
 - simulate 128k/512k patterns?
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- take special runs, improve calibrations
 - attempt to tune realistic model on test run data
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- a lot of work, needs to converge in < two weeks

Conclusions:

- cleaned up svt timing distributions
- implemented simple linear timing model
- simple model measures:
 - 30-45 ns/hit processing time
 - 250-300/ns combination processing time
- can work in a pinch, residual tails potentially a problem
- rough environment model established
- problems at high luminosity, working on fixing
- quality of timing prediction limited by quality of environment (N_{combs}) prediction for high luminosity
- also working on testing models with ModSim, environment scaling, parametrizing improvements